Independent Study-Remotely controlled Excavator

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Create a mini excavator



Introduction of the project

Introduce excavator at each stage



First version-Mechanical arm

1st Version – Mechanical Arm

A simple version of mechanical arm Hardware:

- Bamboo chopsticks
- Tape, hot glue
- Motors(sg90)
- Joystick

Software:

- Arduino IDE











ARDUINO

Use Arduino to write programs

Dictures of work



Connecting motors and joystick to the Arduino board.



Second version-Mechanical arm

2nd Version – Mechanical Arm

Hardware:

- Foam board
- Tape, hot melt adhesive
- Motors(sg90)
- Joystick
- Screws

Software:

- Arduino IDE





Changes made to the base:

1.Use three-bar linkage mechanism to make the arm move

2.Add motors and gearwheels at the bottom

1.Reduce weight at the top of the structure2.Make the base turn

Changes to the base







Third version: Mini-excavator







Use App Inventor to build an app to control the excavator.





Difficulties with App Inventor

Debugging example:



Problems- 3D printing

Sizing problem Curved base

0.3 times







Problems- 3D printing (ജ)



Problems- 3D printing

Printing the gear wheels







3 different models





Motor



The motor can't turn because of the weight.









